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The deal.II Library, Version 9.0

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Abstract: This paper provides an overview of the new features of the finite element library deal.II version 9.0.

1 Overview

deal.II version 9.0.0 was released May 11, 2018. This paper provides an overview of the new features of this major release and serves as a citable reference for the deal.II software library version 9.0. deal.II is an object-oriented finite element library used around the world in the development of finite element solvers. It is available for free under the GNU Lesser General Public License (LGPL) from the deal.II homepage at http://www.dealii.org/.

The major changes of this release are:

- Improved support for curved geometries;
- Support for particle-in-cell methods;
- Dedicated support for automatic differentiation;
- Interfaces to more external libraries and programs;
- C++11 is now both required and used;
- Support for GPU computations;
- Support for face integrals and significant improvements of the matrix-free framework;
- Two new tutorial programs step-59 and step-60.

These will all be discussed in more detail in the following section. In addition, this release contains the following changes:

- `deal.II` has made extensive use of both the Clang-Tidy [47] and Coverity Scan [21] static analysis tools for detecting bugs and other issues in the code. For example, around 260 issues were detected and fixed using the latter tool.
- `LinearOperator`, a flexible template class that implements the action of a linear operator (see [49]), now supports computations with Trilinos, Schur complements, and linear constraints. This class is, as of this release, the official replacement for about half a dozen similar (but less general) classes, such as `FilteredMatrix`, `IterativeInverse`, and `PointerMatrix`.
- New non-standard quadrature rules: A number of non-standard, special-purpose quadrature rules have been implemented. Among these are ones for (i) truncating standard formulas to simplical domains (`QSimplex`); (ii) singular transformations of the unit cell to the unit simplex (`QDuffy`); (iii) composition of simplical quadrature rules to a combined rule on the unit cell (`QSplit`); and (iv) transformation of the unit square to polar coordinates (`QTrianglePolar`). These quadrature rules greatly help when integrating singular functions or on singular domains. They are mainly used in Boundary Element Methods.
- Support for complex-valued vectors at the same level as real-valued vectors.
- A new python tutorial program tutorial-1; as well as updates to step-37. In addition, the separate code gallery of `deal.II` has gained a number of new entries.
- Improved support for user-defined run-time parameters: A new class `ParameterAcceptor` has been added to the library. Users should write classes inheriting from that class to manage parameters stored by a `ParameterHandler`. If the managing class is derived from `ParameterAcceptor` and all parameters are declared by either `parse_parameters` and `declare_parameters` or `ParameterAcceptor::add_parameter`, then both the declaration and parsing of parameter files will be (instead of using ad-hoc calls to `ParameterHandler` methods) automatically managed by the `ParameterAcceptor::initialize` method, which greatly simplifies parameter management in user codes.
- A new caching mechanism for expensive grid computations: this version introduces a new class `GridTools::Cache` that caches computationally intensive information about a `Triangulation`.

  This class allows the user to query some of the data structures constructed using functions in the `GridTools` namespace. This data is then computed only once, and cached inside this class for faster access whenever the triangulation has not changed. The cache is marked for

update by the `Triangulation` itself using signals so that data is properly invalidated upon mesh refinement and coarsening.

Some of the methods in `GridTools` and `FEFieldFunction` already use this cache to avoid repeated calls to the same expensive methods. This results in important speed-ups for computationally heavy methods like `GridTools::compute_point_locations`.

– A new `MeshWorker::mesh_loop` function has been added that performs the same tasks of the `MeshWorker::loop` function without forcing the users to adhere to a specific interface.

– A new method `GridTools::distributed_compute_point_locations` to perform the same tasks of `GridTools::compute_point_locations` with arbitrary points on a distributed mesh has been added. The current implementation uses vectors of `BoundingBoxes` to manage the communication to other processes of points which cannot be computed locally.

Beyond these changes, the changelog lists more than 330 other features and bugfixes.

2 Significant changes to the library

This release of `deal.II` contains a number of large and significant changes that will be discussed in the following sections. It of course also contains a vast number of smaller changes and added functionality; the details of these can be found in the file that lists all changes for this release, see [46]. (The file is also linked to from the web site of each release as well as the release announcement.)

2.1 Improved support for curved geometries

`deal.II` has had the ability to attach *manifold descriptions* to all parts of a geometry since the 8.2 release. These descriptions are used to place new vertices during mesh refinement, to determine the mapping between the reference and real cells, and in a number of other contexts. These classes, inheriting from `Manifold`, describe coordinate transformations in a general way and completely supersede the older classes inheriting from `Boundary`. However, for historical reasons, manifold descriptors have used some of the same code paths as boundary indicators, which were only intended for marking what parts of the boundary correspond to what boundary conditions. Put another way: under certain circumstances a boundary indicator was also interpreted as a manifold indicator.

The current release severs this connection: Boundary indicators and manifold descriptions are now entirely separated. This means that `boundary_id`s are only used to set boundary conditions and `manifold_id`s are only used to set geometry descriptions. The old compatibility code for using boundary indicators as manifold indicators has been removed and all usages of the old-style `Boundary` objects (even with manifold ids) are now deprecated.

There are also numerous improvements to the available manifold descriptions. First, the manifold smoothing algorithms applied in the `Triangulation` class and `MappingQGeneric` have been changed from the old Laplace-style smoothing to a transfinite interpolation that linearly blends between the descriptions on the faces around a cell. The old transformation introduced boundary layers inside cells that prevented convergence rates from exceeding 3.5 in the global L^2 errors for typical settings. This change also considerably improves mesh quality in situations where curved descriptions are only applied to the boundary rather than the whole volume. This concept was also introduced as a new manifold class `TransfiniteInterpolationManifold`, which allows to apply this type of smoothing not only in the cells close to the boundary but over a full coarse (level 0) cell.

Finally, every function in the `GridGenerator` namespace now attaches a default manifold to the curved parts of the domain described by the generated mesh, and sets reasonable defaults for manifold indicators both in the domain and on the boundary.

2.2 Support for particle-in-cell methods

While `deal.II` is a package intended to solve problems with the finite element method – i.e., using continuous or discontinuous *fields* –, it is often convenient in fluid dynamics problems to couple the continuum description of phenomena with particles. These particles, advected along with the numerical approximation of the flow field, are then either used to visualize properties of the flow, or to advect material properties such as the viscosity of inhomogeneous mixtures of fluids. If each particle is associated with the cells of a mesh, these methods are often referred to as particle-in-cell (PIC).

`deal.II` now has a dedicated particles module. The module provides a base class `Particle` that represents a particle with position, an ID number and a variable number of properties. They are jointly represented by a `ParticleHandler` class that manages the storage and handling of all particles. In parallel simulations, this class also distributes the particles among the subdomains of the parallel process and supports efficient data transfer during mesh refinement and checkpoint/restart phases.

A much more detailed view of the underlying algorithms can be found in [29]. A longer report is at [28]. The implementation here originated in the `Aspect` code, see [42, 33].

2.3 Dedicated support for automatic differentiation

Automatic differentiation (AD) is often used to automatically derive residuals and their linearization from a stored energy functional, and to derive Jacobian matrices from residual vectors for simulations that use complicated material models. Examples of its application can be found widely within nonlinear solid mechanics, coupled multiphysics problems, as well as for nonlinear viscosity models in fluid flow.

`deal.II` has had a tutorial program (step-33) since 2007 that demonstrates this technique based on the Trilinos Sacado [17] package, but the functionality was not available pervasively throughout deal.II. This has changed with release 9.0 where support for differentiation is now available using a selection of "white-listed" libraries (namely ADOL-C [32] and Sacado) and a subset of their supported number types. Currently, we offer support for the following cases:

- ADOL-C taped (n-differentiable),
- ADOL-C tapeless (once differentiable),
- Sacado dynamic forward (once differentiable),
- Sacado reverse (once differentiable),
- Sacado nested dynamic forward (twice differentiable), and
- Sacado nested reverse and dynamic forward (twice differentiable).

In practice, this support means that these ADOL-C and Sacado data types can be used as the underlying "scalar" in the `FEValues`, `FEValuesViews`, `Tensor`, `SymmetricTensor`, and related classes that are generally used to assemble linear systems and right hand sides. Given the updated capabilities of the library, there is now a dedicated module that presents the AD compatibility and capabilities of the `deal.II` libraries. Furthermore, the use of Sacado is demonstrated in a much more simplified and transparent manner in a modernized version of an existing "code gallery" example [53].

To date it remains necessary for the user to manage the initialization of AD independent variables and the resultant calls to the AD dependent variables in order to initiate the computation of derivatives. In the next release we expect to provide a unified interface to these AD libraries, which will hide these library-dependent implementational details and facilitate switching between the supported libraries and AD number types based on the user's requirements.

2.4 New interfaces to external libraries and programs

deal.II has always tried to leverage high-quality implementations of algorithms available through other open source software, rather than re-implementing their functionality. (A list of interfaces to other packages is given in Section 3.) As part of the current release, we have written several new interfaces as discussed in the following.

Assimp, the Open Asset Import Library. Assimp [57] can be used to read about 40 different 3D graphics formats. A subset of these formats can be now be read from within deal.II to generate two-dimensional meshes, possibly embedded in a three-dimensional space.

nanoflann, a library for building and querying k-d trees of datasets. Operations such as finding the vertex or cell closest to a given evaluation point occur frequently in many applications that use unstructured meshes. While the naive algorithm is linear in the number of vertices or cells, many such operations can be made significantly faster by building a k-d tree data structure that recursively subdivides a k dimensional space. The nanoflann library [19] provides such a data structure and allows querying it, either for closest points (e.g., when finding the closest vertex) or for searching the points that fall within a radius of a target point. This functionality is now available via deal.II interfaces.

ROL, a Rapid Optimization Library. ROL [56] is a package for large-scale optimization. deal.II can now use the state-of-the-art algorithms in ROL to solve unconstrained and constrained optimization problems as well as optimization problems under uncertainty. deal.II provides an interface to ROL's (abstract) vector class using the adapter software pattern. Through such an interface any vector class in deal.II following certain interface requirements can be used to define a ROL objective function.

ScaLAPACK, a parallel dense linear algebra library for distributed memory machines. ScaLAPACK [18] provides block-cyclic matrix distribution over 2D process grids. The functionality and interface of our wrappers is similar to the LAPACK [4] wrappers for serial dense linear algebra, namely matrix-matrix multiplication, Cholesky and LU factorizations, eigensolvers, SVD, least squares, pseudoinverses and save/load operations using either serial or parallel HDF5 [58]. All of this functionality is available even in cases where the number of MPI processes does not match the numbers of processes in the 2D process grid used to distribute a matrix.

As part of this effort, we have also improved LAPACK support: there are now methods to perform rank-1 updates/downdates, Cholesky factorizations, to compute the trace and determinant, as well as estimate the reciprocal condition number. We also now support configuration with 64-bit BLAS.

SUNDIALS, a SUite of Nonlinear and DIfferential/ALgebraic Equation Solvers. Solving nonlinear algebraic and differential equations is both a common task and one that often requires sophisticated globalization algorithms for efficiency and reliability. SUNDIALS [38] provides these in a widely used format, both sequentially and in parallel.

deal.II now has interfaces to SUNDIALS's ARKode, IDA, and KINSOL sub-packages. ARKode is a solver library that provides adaptive-step time integration. IDA is a package for the solution of differential-algebraic equations systems in the form $F(t, y, y') = 0$. KINSOL is a solver for nonlinear algebraic systems.

2.5 Use of C++11

deal.II first offered support for a subset of C++11 features in version 6.2, released in 2009. The current release is the first to *require* a C++11 compiler.

Many parts of the code base have been rewritten to both support and use the new features of C++11. In particular, deal.II now makes extensive use of move semantics as well as range-based `for` loops with `auto` type deduction of iterator variables. We have also largely replaced `push_back()` by `emplace_back()` when adding elements to collections more efficiently.

Finally, we have changed the entire code base to avoid using raw pointers and instead use `std::unique_ptr` and `std::shared_ptr` where possible to make memory management more reliable. These changes include some minor incompatibilities: all `clone()` functions (such as `FiniteElement::clone()` and `Mapping::clone()`) now return `std::unique_ptr`s instead of C-style raw pointers. Indeed, nearly all interfaces throughout the library that return a pointer now return either a `std::shared_ptr` or a `std::unique_ptr`, thereby clarifying object ownership and avoiding memory leaks.

2.6 Support for GPU computations

Heterogeneous computing is becoming more prevalent in supercomputing and this is a trend that is expected to continue in the future. In particular, the use of GPUs has been increasing during the last few years.

This release of `deal.II` adds support for GPUs both for matrix-based and matrix-free applications. For matrix-based applications, we rely on cuSPARSE [23] and cuSOLVER [22] for operations on sparse matrices such as matrix-vector multiplication and for direct solvers. We have introduced a new type of sparse matrix, `CUDAWrappers::SparseMatrix`, which moves onto the device a `deal.II SparseMatrix` and changes the format of the underlying data to the appropriate CSR format used by cuSPARSE. We also have added wrappers for Cholesky and LU factorizations provided by cuSOLVER. In practice, a user would assemble the system matrix and right hand side vector on the host and then move them to the device. At this point, the linear system would be solved on the device and the solution would be moved back to the host.

We also have some support for matrix-free computation on a GPU. For now, the evaluation of the operator is limited to meshes without hanging nodes.

2.7 Extended matrix-free capabilities

The matrix-free infrastructure in `deal.II` was significantly overhauled for this release. The major new contribution is the support of face integrals through a new class `FEFaceEvaluation`. The new class has a similar interface as the existing `FEEvaluation` class, and applies SIMD vectorization over several faces in analogy to the intra-cell vectorization in FEEvaluation. Discontinuous Galerkin operators are implemented defining two face functions, one for interior and one for boundary faces, in addition to the cell function. These kernels for the matrix-free operator evaluation are now invoked by the new function `MatrixFree::loop`. The data structures have been particularly tuned for typical discontinuous Galerkin setups involving operators with first and second spatial derivatives. Both data access and computations have been thoroughly optimized and compared to the performance boundaries of the hardware. Furthermore, the support for AVX-512 instructions in the matrix-free framework was extended, adding new `gather` and `scatter` intrinsics for the indirect access to vector entries where appropriate.

To give an example of the algorithmic improvements, the computation of the values and gradients on all quadrature points for cell integrals has been significantly improved, yielding 10–20% better performance for cases where the kernels are compute bound. For the example of the reference cell gradient of a solution field $\mathbf{u}$ in three space dimensions, the new release applies the following change:

$$\text{previous: } \begin{bmatrix} D_1 \otimes S_2 \otimes S_3 \\ S_1 \otimes D_2 \otimes S_3 \\ S_1 \otimes S_2 \otimes D_3 \end{bmatrix} \mathbf{u} \quad \rightsquigarrow \quad \text{new: } \begin{bmatrix} D_1^{\text{co}} \otimes I_2 \otimes I_3 \\ I_1 \otimes D_2^{\text{co}} \otimes I_3 \\ I_1 \otimes I_2 \otimes D_3^{\text{co}} \end{bmatrix} \Big[S_1 \otimes S_2 \otimes S_3 \Big] \mathbf{u}.$$

The matrices S_i contain the values of the one-dimensional shape functions in one-dimensional quadrature points and D_i their derivatives. When applied with the usual sum factorization implementation described, for example, in [43], the old kernels amounted to 9 partial summations – or rather 8 in the previous implementation of `deal.II` because the application of S_1 for the y and z components of the gradient can be merged. The new code performs a basis transformation

to a related basis with derivative matrix $D_i = D_i^{\text{co}} S_i$, which is the basis of Lagrange polynomials in the points of the quadrature. This change reduces the number of partial sums to only 6 for the gradient, as the action of the unit matrices I_i needs not be implemented. In isolation, this spectral element-like evaluation was previously available in `deal.II` for collocation between nodal points and quadrature, but not used for general bases. A more detailed description of the matrix-free components and their performance characteristics is given in the preprint [44].

2.8 Tutorial and code gallery programs

Two new tutorial programs were added to this release of `deal.II`. The tutorial program `step-59` presents a matrix-free solver for the Poisson equation discretized with the interior penalty discontinuous Galerkin method. The implementation is based on the new matrix-free functions described in Subsection 2.7. The new class `TensorProductMatrixSymmetricSum` is used to construct a block-Jacobi smoother in a geometric multigrid preconditioner, based on the definition of the inverse of a tensor product matrix through tensor products. As compared to a matrix-based block-Jacobi method, this approach considerably reduces the memory access and also the complexity at high polynomial degrees, going from $O(k^{2d})$ arithmetic operations per cell for degree k in d dimensions to only $O(k^{d+1})$. The new tutorial demonstrates the outstanding performance of `deal.II`'s matrix-free module, solving the Poisson equation with 191 million degrees of freedom at degree $k = 8$ on a workstation with 12 cores in about a minute.

The tutorial program `step-60` shows how to perform computations on non-matching grids, and it presents advanced manipulation of `ParameterHandler` objects using the new `ParameterAccessor` and `ParameterAccessorProxy` classes. `step-60` solves a Poisson problem on a domain Ω, subject to equality constraints defined on an embedded domain Γ. The embedded domain can be of co-dimension one or co-dimension zero, and its definition is independent with respect to Ω. In order to enforce correctly the constraints, a non-matching coupling matrix needs to be constructed. This is achieved using the new `NonMatching::create_coupling_sparsity_pattern` and `NonMatching::create_coupling_mass_matrix` functions that exploit new functionality in the `GridTools` namespace.

`deal.II` has a separate "code gallery" that consists of programs shared by users as examples of what can be done with `deal.II`. While not part of the release process, it is nonetheless worth mentioning that the set of new programs since the last release covers the following topics:

- The multipoint flux mixed finite element method (MFMFE) applied to the Darcy problem of porous media flow;
- A linearized active skeletal muscle model with application to the simulation concentric contraction of the human biceps brachii;
- A parallel implementation of the Local Discontinuous Galerkin (LDG) method applied to the Poisson equation.

With these additions, the code gallery now contains 10 different applications.

2.9 Incompatible changes

The 9.0 release includes around 75 incompatible changes; see [46]. The majority of these changes should not be visible to typical user codes; some remove previously deprecated classes and functions, and the majority change internal interfaces that are not usually used in external applications. However, some are, such as changes to the interplay between meshes and manifolds, as well as the requirement to use a C++11 compiler (see Sections 2.1 and 2.5). In addition, the following incompatible changes are worth mentioning:

- The `BlockDiagonalMatrix`, `InverseMatrixRichardson`, `IterativeInverse`, `ProductMatrix`, `ProductSparseMatrix`, `TransposeMatrix`, `ScaledMatrix`, `SchurMatrix`, `ShiftedMatrix`, and `ShiftedMatrixGeneralized` classes have been removed. They are now generalized through the `LinearOperator` concept. Several other, similar classes have been deprecated.
- The default partitioner for the `parallel::shared::Triangulation` is now the Trilinos package Zoltan. This functionality was previously provided by the METIS partitioner, but the METIS package has not been actively maintained for a long time, and moreover yields subdivisions that depend on system details such as the random number generator and sorting facilities provided by the operating system; consequently, the partition is not consistent across platforms.
- The class `FE_DGQHermite` now uses a more stable, "Hermite-like" polynomial basis. The change is highly beneficial because it significantly improves the accuracy (in terms of round-off) for this basis and also reduces iteration counts for some iterative solvers with simple preconditioners.
- Many functions that previously returned a raw, C-style pointer now return a `std::unique_ptr` and `std::shared_ptr` where possible to make memory management more reliable.

3 How to cite `deal.II`

In order to justify the work the developers of `deal.II` put into this software, we ask that papers using the library reference one of the `deal.II` papers. This helps us justify the effort we put into it.

There are various ways to reference `deal.II`. To acknowledge the use of the current version of the library, **please reference the present document**. For up to date information and bibtex snippets for this document see:

https://www.dealii.org/publications.html

The original `deal.II` paper containing an overview of its architecture is [10]. If you rely on specific features of the library, please consider citing any of the following:

- For geometric multigrid: [40, 39];
- For distributed parallel computing: [8];
- For *hp* adaptivity: [16];
- For partition-of-unity (PUM) and enrichment methods of the finite element space: [25];
- For matrix-free and fast assembly techniques: [43];
- For computations on lower-dimensional manifolds: [26];
- For integration with CAD files and tools: [34];
- For Boundary Elements Computations: [31];
- For `LinearOperator` and `PackagedOperation` facilities: [48, 49].
- For uses of the `WorkStream` interface: [59].

`deal.II` can interface with many other libraries:

- ADOL-C [32, 60]
- ARPACK [45]
- Assimp [57]
- BLAS and LAPACK [4]
- cuSOLVER [22]
- cuSPARSE [23]
- Gmsh [30]
- GSL [27]
- HDF5 [58]
- METIS [41]
- MUMPS [1, 2, 3, 50]
- muparser [51]
- nanoflann [19]
- NetCDF [55]
- OpenCASCADE [52]
- p4est [20]
- PETSc [6, 7]
- ROL [56]
- ScaLAPACK [18]
- SLEPc [35]
- SUNDIALS [38]
- TBB [54]
- Trilinos [36, 37]
- UMFPACK [24]

Please consider citing the appropriate references if you use interfaces to these libraries.

Older releases of `deal.II` can be cited as [12, 13, 14, 11, 9, 5].

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