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A MINIMIZATION APPROACH TO THE WAVE EQUATION ON TIME-DEPENDENT DOMAINS

G. DAL MASO AND L. DE LUCA

ABSTRACT. We prove the existence of weak solutions to the homogeneous wave equation on a suitable class of time-dependent domains. Using the approach suggested by De Giorgi and developed by Serra and Tilli, such solutions are approximated by minimizers of suitable functionals in space-time.

KEYWORDS: wave equation, time-dependent domains, minimization

AMS SUBJECT CLASSIFICATIONS: 35L15, 49J10, 35Q74, 74R10, 35L90

INTRODUCTION

Several problems in dynamic fracture mechanics lead to the study of the wave equation in time-dependent domains (see [6, 7, 3]). The main difficulty is that at every time t the solution belongs to a different function space V_t . It is not restrictive to assume that all spaces V_t are embedded in a given Hilbert space H .

In the case of fracture mechanics, a common situation is $V_t = H^1(\Omega \setminus \Gamma_t)$ and $H = L^2(\Omega)$, where Ω is a domain in \mathbb{R}^d and Γ_t is a closed $(d-1)$ -dimensional subset of Ω , representing the crack at time t . A natural assumption on Γ_t is that it is monotonically increasing with respect to t , thus encoding the fact that, once created, a crack cannot disappear. As a consequence, the spaces V_t are increasing in time too.

To deal with possibly irregular cracks a more general increasing family of spaces has been considered in [2]: $V_t = GSBV_2^2(\Omega, \Gamma_t)$, defined as the space of functions $u \in GSBV(\Omega)$ such that $u \in L^2(\Omega)$, $\nabla u \in L^2(\Omega; \mathbb{R}^d)$, and $J_u \subset \Gamma_t$ (see [1] for the definition and properties of these spaces and for the definition of the approximate gradient ∇u and of the jump set J_u).

Given $u^0 \in V_0$ and $u^1 \in H$, the Cauchy problem we are interested in is formally written as

$$(0.1) \quad \begin{cases} u''(t) + Au(t) = 0 & \text{for a.e. } t > 0, \\ u(t) \in V_t & \text{for a.e. } t > 0, \\ u(0) = u^0, u'(0) = u^1, \end{cases}$$

where $'$ denotes the time derivative and A is a continuous and coercive linear operator ($A = -\Delta$ with homogeneous Neumann boundary conditions in the examples considered above).

The existence of a solution for (0.1) has already been proven in [2], through a time-discrete approach, by solving suitable incremental minimum problems and then passing to the limit as the time step tends to zero.

The purpose of this paper is to prove that a solution of (0.1) can be approximated by global minimizers of suitable energy functionals defined as integrals on $[0, \infty)$ with respect to time. On the one hand this shows a link between solutions of the hyperbolic problem (0.1) and solutions of minimum problems for integral functionals on the same time domain. On the other hand this result provides a new proof of the existence of a solution to (0.1).

The seminal idea of this approximation process goes back to a conjecture by De Giorgi [5] on the nonlinear wave equation. Such a conjecture has been proven by Serra and Tilli in [8] and, in a more general setting, in [9].

In our paper we extend their result to the case of time-dependent domains. To illustrate the global minimization approach in our setting, we focus on the model case $V_t = H^1(\Omega \setminus \Gamma_t)$ and $A = -\Delta$. The main idea is to associate to the Cauchy problem (0.1) a functional of the form

$$(0.2) \quad \mathcal{F}_\varepsilon(u) := \frac{1}{2} \int_0^\infty e^{-t/\varepsilon} \left(\varepsilon^2 \|u''(t)\|_{L^2(\Omega)}^2 + \|\nabla u(t)\|_{L^2(\Omega; \mathbb{R}^d)}^2 \right) dt,$$

This functional is to be minimized, for every fixed $\varepsilon > 0$, among all the functions $t \mapsto u(t)$ satisfying the initial conditions $u(0) = u^0$ and $u'(0) = u^1$ and the time-dependent constraint $u(t) \in V_t$ for a.e. $t > 0$. Once the existence of a minimizer u_ε is proven, the Euler-Lagrange equation of (0.2) formally reads as

$$\varepsilon^2 u_\varepsilon''''(t) - 2\varepsilon u_\varepsilon'''(t) + u_\varepsilon''(t) - \Delta u_\varepsilon(t) = 0 \quad \text{in } \Omega \setminus \Gamma_t,$$

and hence, letting $\varepsilon \rightarrow 0$, one *formally* obtains a solution to the wave equation in (0.1).

As mentioned above, a quite general scheme to pass to the limit rigorously has been introduced by Serra and Tilli in [9] when time-dependent constraint $u(t) \in V_t$ is not present. The proof consists in finding suitable estimates on the minimizers u_ε of the functionals \mathcal{F}_ε and to exploit these estimates in order to obtain, by compactness, the convergence of u_ε to a weak solution u to the wave equation.

In this paper we implement this scheme in the case of time-dependent domains. This requires some changes in the proof, since all competitors of the minimum problem for (0.2) must satisfy the constraint $u(t) \in V_t$ for a.e. $t > 0$.

The main change is in the proof of the key estimate for $u_\varepsilon(t)$, which is obtained in [9] by using an inner variation $u_\varepsilon(\varphi_\delta(t))$ for a suitable function $\varphi_\delta: [0, \infty) \rightarrow [0, \infty)$. Since in our case we have to require that $u_\varepsilon(\varphi_\delta(t)) \in V_t$ for a.e. $t > 0$, this variation is admissible only if $\varphi_\delta(t) \leq t$ for a.e. $t > 0$. By the technical definition of φ_δ , this leads to the constraint $\delta > 0$. Therefore the standard comparison between the functional on $u_\varepsilon(\varphi_\delta(t))$ and on the minimizer $u_\varepsilon(t)$, in the limit as $\delta \rightarrow 0+$, gives only an inequality, instead of the equality proven in [9, formula (4.7)]. This inequality, however, turns out to be enough to obtain the other estimates of [9] with minor changes.

A further difficulty appears when proving that the limit u of u_ε is a weak solution of (0.1), since also the test functions η must satisfy the constraint $\eta(t) \in V_t$ for a.e. $t > 0$. Therefore, to adapt the proof of [9], we have to approximate an arbitrary test function η satisfying the constraint $\eta(t) \in V_t$ for a.e. $t > 0$ by sums of functions of the form $\varphi(t)v$ with $v \in V_s$ and $\varphi \in C^2(\mathbb{R})$ with $\text{supp}(\varphi) \subset [s, \infty)$, which still satisfy the constraint.

1. DESCRIPTION OF THE PROBLEM

1.1. Setting. To study the wave equation in time-dependent domains we adopt the functional setting introduced in [4]. Let H be a separable Hilbert space and let $(V_t)_{t \in [0, \infty)}$ be a family of separable Hilbert spaces with the following properties

- (H1) for every $t \in [0, \infty)$ the space V_t is contained and dense in H with continuous embedding;
- (H2) for every $s, t \in [0, \infty)$, with $s < t$, V_s is a closed subspace of V_t with the induced scalar product.

The scalar product in H is denoted by (\cdot, \cdot) and the corresponding norm by $\|\cdot\|$. The norm in V_t is denoted by $\|\cdot\|_t$. By (H2) for every $0 \leq s < t$ we have $\|v\|_s = \|v\|_t$ for every $v \in V_s$.

The dual of H is identified with H , while for every $t \in [0, T]$ the dual of V_t is denoted by V_t^* . Note that the adjoint of the continuous embedding of V_t into H provides a continuous embedding of H into V_t^* and that H is dense in V_t^* . Let $\langle \cdot, \cdot \rangle_t$ be the duality product between V_t^* and V_t and let $\|\cdot\|_t^*$ be the corresponding dual norm. Note that $\langle \cdot, \cdot \rangle_t$ is the unique continuous bilinear map on $V_t^* \times V_t$ satisfying

$$(1.1) \quad \langle h, v \rangle_t = (h, v) \quad \text{for every } h \in H \text{ and } v \in V_t.$$

Let $V_\infty := \bigcup_{t \geq 0} V_t$ and let $a: V_\infty \times V_\infty \rightarrow \mathbb{R}$ be a bilinear symmetric form satisfying the following conditions:

(H3) continuity: there exists $M_0 > 0$ such that

$$(1.2) \quad |a(u, v)| \leq M_0 \|u\|_t \|v\|_t \quad \text{for every } t \geq 0 \text{ and every } u, v \in V_t;$$

(H4) coercivity: there exist $\lambda_0 \geq 0$ and $\nu_0 > 0$ such that

$$(1.3) \quad a(u, u) + \lambda_0 \|u\|^2 \geq \nu_0 \|u\|_t^2 \quad \text{for every } t \geq 0 \text{ and every } u \in V_t;$$

(H5) positive semidefiniteness:

$$(1.4) \quad a(u, u) \geq 0 \quad \text{for every } u \in V_\infty.$$

For every $\tau, t \in [0, \infty)$ let $A_\tau^t: V_t \rightarrow V_\tau^*$ be the continuous linear operator defined by

$$(1.5) \quad \langle A_\tau^t u, v \rangle_\tau := a(u, v) \quad \text{for every } u \in V_t \text{ and } v \in V_\tau.$$

Note that

$$(1.6) \quad \|A_\tau^t u\|_\tau^* \leq M_0 \|u\|_t \quad \text{for every } u \in V_t.$$

Finally, we set $Q(u) := a(u, u)$ for every $u \in V_\infty$.

Definition 1.1. Given $T > 0$, we define $\mathcal{W}_T^{0,1} := L^2((0, T); V_T) \cap H^1((0, T); H)$, with the Hilbert space structure induced by the scalar product

$$(u, v)_{\mathcal{W}_T^{0,1}} = (u, v)_{L^2((0, T); V_T)} + (u', v')_{L^2((0, T); H)},$$

where u' and v' denote the distributional derivatives. The norm induced by the scalar product $(\cdot, \cdot)_{\mathcal{W}_T^{0,1}}$ is denoted by $\|\cdot\|_{\mathcal{W}_T^{0,1}}$. Moreover, we define

$$\mathcal{V}_T^{0,1} := \{u \in \mathcal{W}_T^{0,1} : u(t) \in V_t \text{ for a.e. } t \in (0, T)\},$$

and note that it is a closed subspace of $\mathcal{W}_T^{0,1}$.

Analogously, we define $\mathcal{W}_T^{0,2} := L^2((0, T); V_T) \cap H^2((0, T); H)$, with the Hilbert space structure induced by the scalar product

$$(u, v)_{\mathcal{W}_T^{0,2}} = (u, v)_{L^2((0, T); V_T)} + (u', v')_{L^2((0, T); H)} + (u'', v'')_{L^2((0, T); H)},$$

and the space

$$\mathcal{V}_T^{0,2} := \{u \in \mathcal{W}_T^{0,2} : u(t) \in V_t \text{ for a.e. } t \in (0, T)\},$$

which is a closed subspace of $\mathcal{W}_T^{0,2}$.

Finally, $\mathcal{V}^{0,1}$ (resp. $\mathcal{V}^{0,2}$) is defined as the space of functions $u: (0, +\infty) \rightarrow H$ whose restrictions to $(0, T)$ belong to $\mathcal{V}_T^{0,1}$ (resp. $\mathcal{V}_T^{0,2}$) for every $T > 0$.

Remark 1.2. It is well known that every function $u \in H^1((0, T); H)$ (resp. $u \in H^2((0, T); H)$) admits a representative, still denoted by u , which belongs to the space $C^0([0, T]; H)$ (resp. $C^1([0, T]; H)$). With this convention we have $\mathcal{V}_T^{0,1} \subset C^0([0, T]; H)$ (resp. $\mathcal{V}_T^{0,2} \subset C^1([0, T]; H)$) for every $T > 0$.

Definition 1.3. We say that u is a weak solution of the equation

$$(1.7) \quad u''(t) + A_t^t u(t) = 0, \quad u(t) \in V_t \quad \text{for } t \in [0, \infty)$$

if $u \in \mathcal{V}^{0,1}$ and for every $T > 0$

$$(1.8) \quad \int_0^T (u'(t), \psi'(t)) dt = \int_0^T a(u(t), \psi(t)) dt$$

for every $\psi \in \mathcal{V}_T^{0,1}$ with $\psi(0) = \psi(T) = 0$.

For every Banach space X let $C_w([0, T]; X)$ be the space of functions $u: [0, T] \rightarrow X$ that are continuous for the weak topology of X .

Remark 1.4. If u is a weak solution of (1.7) with $u \in L^\infty((0, T); V_T)$ and $u' \in L^\infty((0, T); H)$ for every $T > 0$, then [4, Theorem 2.17 and Proposition 2.18] imply that, after a modification on a set of measure zero, $u \in C_w([0, T]; V_T)$ and $u' \in C_w([0, T]; H)$ for every $T > 0$.

1.2. Main results. Throughout the paper we fix $u^0 \in V_0$, $u^1 \in H$, and a sequence $\{u_\varepsilon^1\} \subset V_0$ such that

$$(1.9) \quad \|u_\varepsilon^1 - u^1\|_H \rightarrow 0 \text{ as } \varepsilon \rightarrow 0+ \quad \text{and} \quad \varepsilon \|u_\varepsilon^1\|_0 \leq C_1,$$

for some constant $C_1 > 0$. For every $\varepsilon > 0$ we consider the functional

$$(1.10) \quad \mathcal{F}_\varepsilon(u) := \frac{1}{2} \int_0^\infty e^{-t/\varepsilon} \left(\varepsilon^2 \|u''(t)\|^2 + Q(u(t)) \right) dt,$$

defined on the set

$$(1.11) \quad \mathcal{V}^{0,2}(u^0, u_\varepsilon^1) := \{u \in \mathcal{V}^{0,2} : u(0) = u^0, u'(0) = u_\varepsilon^1\},$$

which is well-defined in view of Remark 1.2.

We now state our main results, which are proven in Sections 2, 3, and 4.

Theorem 1.5. *For every $\varepsilon \in (0, 1)$ the functional \mathcal{F}_ε admits a unique global minimizer u_ε in the set $\mathcal{V}^{0,2}(u^0, u_\varepsilon^1)$. Moreover,*

$$(1.12) \quad \mathcal{F}_\varepsilon(u_\varepsilon) \leq \bar{C}\varepsilon,$$

for some constant $\bar{C} > 0$ depending only on $\|u^0\|_0$ and C_1 .

In particular, if $\varepsilon \|u_\varepsilon^1\|_0 \rightarrow 0$ as $\varepsilon \rightarrow 0+$, then

$$(1.13) \quad \mathcal{F}_\varepsilon(u_\varepsilon) \leq \varepsilon \left(\frac{1}{2} Q(u^0) + r_\varepsilon \right),$$

where $r_\varepsilon \rightarrow 0$ as $\varepsilon \rightarrow 0+$.

Theorem 1.6. *There exists a constant $C > 0$ such that for every $\varepsilon \in (0, 1)$ the minimizer u_ε of \mathcal{F}_ε in $\mathcal{V}^{0,2}(u^0, u_\varepsilon^1)$ satisfies the estimates:*

$$(1.14) \quad \int_t^{t+\tau} Q(u_\varepsilon(s)) ds \leq C\tau \quad \text{for every } t \geq 0, \tau \geq \varepsilon,$$

$$(1.15) \quad \|u_\varepsilon(t)\|^2 \leq C(1+t^2) \quad \text{for every } t \geq 0,$$

$$(1.16) \quad \|u'_\varepsilon(t)\| \leq C \quad \text{for every } t \geq 0.$$

Theorem 1.7. *For every $\varepsilon \in (0, 1)$ let u_ε be the minimizer of \mathcal{F}_ε in $\mathcal{V}^{0,2}(u^0, u_\varepsilon^1)$. Then for every sequence $\{\varepsilon_n\} \subset (0, 1)$, with $\varepsilon_n \rightarrow 0$ as $n \rightarrow \infty$, there exist a subsequence, not relabeled, and a weak solution u of (1.7) such that $u_{\varepsilon_n} \rightharpoonup u$ weakly in $\mathcal{W}_T^{0,1}$ for every $T > 0$. Moreover the following properties hold:*

- (a) *weak continuity: $u \in C_w([0, T]; V_T)$ and $u' \in C_w([0, T]; H)$ for every $T > 0$;*
- (b) *initial conditions: $u(0) = u^0$ and $u'(0) = u^1$.*

If, in addition, $\varepsilon \|u_\varepsilon^1\|_0 \rightarrow 0$ as $\varepsilon \rightarrow 0+$, then the following energy inequality holds:

$$(1.17) \quad \|u'(t)\|^2 + Q(u(t)) \leq \|u^1\|^2 + Q(u^0) \quad \text{for every } t > 0.$$

2. PROOF OF THEOREM 1.5

Before proving our results we introduce a change of variables that will be useful throughout the paper.

Remark 2.1. For every $\varepsilon > 0$ and every $T > 0$ we set

$$\begin{aligned} \mathcal{W}_{\varepsilon, T}^{0,2} &:= L^2((0, T); V_{\varepsilon T}) \cap H^2((0, T); H), \\ \mathcal{V}_{\varepsilon, T}^{0,2} &:= \{v \in \mathcal{W}_{\varepsilon, T}^{0,2} : v(t) \in V_{\varepsilon t} \text{ for a.e. } t \in (0, T)\}. \end{aligned}$$

Note that $\mathcal{W}_{\varepsilon, T}^{0,2}$ is a Hilbert space with the scalar product

$$(u, v)_{\mathcal{W}_{\varepsilon, T}^{0,2}} = (u, v)_{L^2((0, T); V_{\varepsilon T})} + (u', v')_{L^2((0, T); H)} + (u'', v'')_{L^2((0, T); H)},$$

and $\mathcal{V}_{\varepsilon, T}^{0,2}$ is a closed subspace of $\mathcal{W}_{\varepsilon, T}^{0,2}$. Furthermore, $\mathcal{V}_\varepsilon^{0,2}$ denotes the space of functions $u: [0, \infty) \rightarrow H$ whose restrictions to $(0, T)$ belong to $\mathcal{V}_{\varepsilon, T}^{0,2}$ for every $T > 0$. By Remark 1.2 every $u \in \mathcal{W}_{\varepsilon, T}^{0,2}$ admits a representative, still denoted by u , which belongs to $C^1([0, T]; H)$. With this convention we have $\mathcal{V}_{\varepsilon, T}^{0,2} \subset C^1([0, T]; H)$ for every $T > 0$. Finally, we define

$$\mathcal{V}_\varepsilon^{0,2}(u^0, \varepsilon u_\varepsilon^1) := \{v \in \mathcal{V}_\varepsilon^{0,2} : v(0) = 0, v'(0) = \varepsilon u_\varepsilon^1\}.$$

It is easy to see that if $u \in \mathcal{V}^{0,2}(u^0, u_\varepsilon^1)$, then the function v defined by

$$(2.1) \quad v(t) := u(\varepsilon t)$$

belongs to $\mathcal{V}_\varepsilon^{0,2}(u^0, \varepsilon u_\varepsilon^1)$ and

$$(2.2) \quad \mathcal{F}_\varepsilon(u) = \varepsilon \mathcal{G}_\varepsilon(v),$$

where

$$\mathcal{G}_\varepsilon(v) := \frac{1}{2} \int_0^\infty e^{-t} \left(\frac{\|v''(t)\|^2}{\varepsilon^2} + Q(v(t)) \right) dt.$$

In view of Remark 2.1, Theorem 1.5 is a consequence of the following result for the functional \mathcal{G}_ε .

Theorem 2.2. *For every $\varepsilon \in (0, 1)$ the functional \mathcal{G}_ε admits a unique global minimizer v_ε in the class $\mathcal{V}_\varepsilon^{0,2}(u^0, \varepsilon u_\varepsilon^1)$. Moreover,*

$$(2.3) \quad \mathcal{G}_\varepsilon(v_\varepsilon) \leq \bar{C},$$

for some constant $\bar{C} < \infty$ depending only on $\|u^0\|_0$ and C_1 .

Furthermore $u_\varepsilon(t) := v_\varepsilon(\frac{t}{\varepsilon})$ is the unique global minimizer of \mathcal{F}_ε in $\mathcal{V}^{0,2}(u^0, u_\varepsilon^1)$ and satisfies (1.12).

Finally, if $\varepsilon \|u_\varepsilon^1\|_0 \rightarrow 0$ as $\varepsilon \rightarrow 0+$, then

$$(2.4) \quad \mathcal{G}_\varepsilon(v_\varepsilon) \leq \frac{1}{2}Q(u^0) + r_\varepsilon,$$

where $r_\varepsilon \rightarrow 0$ as $\varepsilon \rightarrow 0$ and u_ε satisfies (1.13).

Proof. Fix $\varepsilon > 0$ and set $v(t) := u^0 + \varepsilon t u_\varepsilon^1$ for every $t \geq 0$. Note that $v \in \mathcal{V}_\varepsilon^{0,2}(u^0, \varepsilon u_\varepsilon^1)$, since $u^0, u_\varepsilon^1 \in V_0 \subset V_t$ for every $t \geq 0$. By (H3) and by (1.9), we have

$$(2.5) \quad \mathcal{G}_\varepsilon(v) = \frac{1}{2} \int_0^\infty e^{-t} Q(v(t)) dt \leq \frac{1}{2} Q(u^0) + M_0 \varepsilon \|u_\varepsilon^1\|_0 (\varepsilon \|u_\varepsilon^1\|_0 + \|u^0\|_0) \leq \bar{C},$$

where \bar{C} is a constant depending only on C_1 and $\|u^0\|_0$. Note that, if $\varepsilon \|u_\varepsilon^1\|_0 \rightarrow 0$ as $\varepsilon \rightarrow 0+$, then by (2.3) it follows that

$$(2.6) \quad \mathcal{G}_\varepsilon(v) \leq \frac{1}{2} Q(u^0) + r_\varepsilon,$$

where $r_\varepsilon \rightarrow 0$ as $\varepsilon \rightarrow 0$.

In particular, \mathcal{G}_ε has a finite infimum and (2.3) (as well as (2.4)) follows as soon as \mathcal{G}_ε has an absolute minimizer v_ε . To show this, consider a minimizing sequence $\{v_{\varepsilon,n}\} \subset \mathcal{V}_\varepsilon^{0,2}(u^0, \varepsilon u_\varepsilon^1)$ and fix $T > 0$. By the very definition of \mathcal{G}_ε and by (2.5),

$$(2.7) \quad \int_0^T \|v_{\varepsilon,n}''(t)\|^2 dt \leq e^T \int_0^T e^{-t} \|v_{\varepsilon,n}''(t)\|^2 dt \leq 2\varepsilon^2 e^T \mathcal{G}_\varepsilon(v_{\varepsilon,n}) \leq \varepsilon^2 C_T,$$

for some constant $C_T > 0$. The bound (2.7), together with the boundary conditions

$$(2.8) \quad v_{\varepsilon,n}(0) = u^0 \quad \text{and} \quad v_{\varepsilon,n}'(0) = \varepsilon u_\varepsilon^1,$$

implies

$$(2.9) \quad \|v_{\varepsilon,n}\|_{H^2((0,T);H)} \leq C_{T,\varepsilon}$$

for some constant $C_{T,\varepsilon} > 0$ independent of n . Moreover, by (H2) and (H4), for $t \in [0, T]$ we have

$$\nu_0 \|v_{\varepsilon,n}(t)\|_t^2 = \nu_0 \|v_{\varepsilon,n}(t)\|_t^2 \leq \lambda_0 \|v_{\varepsilon,n}(t)\|^2 + Q(v_{\varepsilon,n}(t))$$

from which, using (2.5) and (2.9), we get

$$\nu_0 \|v_{\varepsilon,n}\|_{L^2((0,T);V_T)}^2 \leq \lambda_0 \|v_{\varepsilon,n}\|_{L^2((0,T);H)}^2 + \int_0^T Q(v_{\varepsilon,n}(t)) dt \leq \hat{C}_{T,\varepsilon}$$

for some constant $\hat{C}_{T,\varepsilon} > 0$ independent of n . It follows that $\|v_{\varepsilon,n}\|_{\mathcal{W}_{\varepsilon,T}^{0,2}}$ is uniformly bounded and hence, up to a subsequence, $v_{\varepsilon,n} \rightharpoonup v_\varepsilon$ in $\mathcal{W}_{\varepsilon,T}^{0,2}$ as $n \rightarrow \infty$, for some $v_\varepsilon \in \mathcal{W}_{\varepsilon,T}^{0,2}$. Moreover, since $\mathcal{V}_{\varepsilon,T}^{0,2}$ is closed, $v_\varepsilon \in \mathcal{V}_{\varepsilon,T}^{0,2}$. By the arbitrariness of T we have $v_\varepsilon \in \mathcal{V}_\varepsilon^{0,2}$ and by (2.8) we get $v_\varepsilon \in \mathcal{V}_\varepsilon^{0,2}(u^0, \varepsilon u_\varepsilon^1)$. Finally, since \mathcal{G}_ε is lower semi-continuous and strictly convex by (H5), v_ε is the unique minimizer of \mathcal{G}_ε in $\mathcal{V}_\varepsilon^{0,2}(u^0, \varepsilon u_\varepsilon^1)$. The statements about $u_\varepsilon(t)$ follow from Remark 2.1. \square

3. PROOF OF THEOREM 1.6

We first introduce some notations. Let v_ε be the minimizer of \mathcal{G}_ε in $\mathcal{V}_\varepsilon^{0,2}(u^0, \varepsilon u_\varepsilon^1)$ and let L_ε be the corresponding Lagrangian defined as

$$(3.1) \quad L_\varepsilon(t) := D_\varepsilon(t) + Q_\varepsilon(t),$$

where

$$(3.2) \quad D_\varepsilon(t) := \frac{\|v_\varepsilon''(t)\|^2}{2\varepsilon^2} \quad \text{and} \quad Q_\varepsilon(t) := \frac{Q(v_\varepsilon(t))}{2}.$$

Moreover, we define the kinetic energy function K_ε as

$$(3.3) \quad K_\varepsilon(t) := \frac{\|v_\varepsilon'(t)\|^2}{2\varepsilon^2}.$$

We shall use the following result, which can be proven as in [9, Lemma 3.4].

Lemma 3.1. *There exists a constant $C > 0$ (depending only on $\|u^0\|_0$, $\|u^1\|$, and C_1 in (1.9)) such that for every $\varepsilon \in (0, 1)$ the minimizer v_ε of \mathcal{G}_ε in $\mathcal{V}_\varepsilon^{0,2}(u^0, \varepsilon u_\varepsilon^1)$ satisfies*

$$(3.4) \quad \int_0^\infty e^{-t} D_\varepsilon(t) dt = \int_0^\infty e^{-t} \frac{\|v_\varepsilon''(t)\|^2}{2\varepsilon^2} dt \leq C,$$

$$(3.5) \quad \int_0^\infty e^{-t} K_\varepsilon(t) dt = \int_0^\infty e^{-t} \frac{\|v_\varepsilon'(t)\|^2}{2\varepsilon^2} dt \leq C.$$

In particular, in view of Lemma 3.1, we have $K_\varepsilon \in W^{1,1}(0, T)$ for all $T > 0$ and

$$(3.6) \quad K_\varepsilon'(t) = \frac{1}{\varepsilon^2} (v_\varepsilon'(t), v_\varepsilon''(t)) \quad \text{for a.e. } t > 0.$$

Following the approach in [9], we introduce the *average operator* \mathcal{A} , defined by

$$(\mathcal{A}f)(s) := \int_s^\infty e^{-(t-s)} f(t) dt, \quad s \geq 0.$$

for every measurable function $f: [0, \infty) \rightarrow [0, \infty]$.

We note that $\mathcal{A}f$ is well defined (possibly ∞) since $f \geq 0$. Moreover, the equality

$$(3.7) \quad \mathcal{A}f(0) = \int_0^\infty e^{-t} f(t) dt,$$

implies that, if $\mathcal{A}f(0) < \infty$, then $\mathcal{A}f$ is absolutely continuous on all intervals $[0, T]$ and

$$(3.8) \quad (\mathcal{A}f)' = \mathcal{A}f - f \quad \text{a.e. in } [0, \infty).$$

In any case, since $\mathcal{A}f \geq 0$, starting from $f \geq 0$ one can iterate \mathcal{A} , and a simple computation gives

$$(3.9) \quad (\mathcal{A}^2 f)(s) = \int_s^\infty e^{-(t-s)} (t-s) f(t) dt,$$

thus in particular

$$(3.10) \quad (\mathcal{A}^2 f)(0) = \int_0^\infty e^{-t} t f(t) dt.$$

Finally, we define the approximate energy

$$(3.11) \quad E_\varepsilon(t) := K_\varepsilon(t) + (\mathcal{A}^2 Q_\varepsilon)(t).$$

The key ingredient in order to prove Theorem 1.6 is given by the following proposition.

Proposition 3.2. *The function E_ε is uniformly bounded and monotonically nonincreasing. More precisely, there exists $C'_1 > 0$, depending only on $\|u^0\|_0$, $\|u^1\|$, and C_1 in (1.9), such that*

$$(3.12) \quad E_\varepsilon(t) \leq C'_1 \quad \text{for every } t \geq 0.$$

Moreover, if $\varepsilon\|u_\varepsilon^1\|_0 \rightarrow 0$ as $\varepsilon \rightarrow 0+$, then

$$(3.13) \quad E_\varepsilon(t) \leq \frac{1}{2}\|u_\varepsilon^1\|^2 + \frac{1}{2}Q(u^0) + \tilde{r}_\varepsilon,$$

where $\tilde{r}_\varepsilon \rightarrow 0$ as $\varepsilon \rightarrow 0+$.

Proof. The proof of Proposition 3.2 closely follows the strategy adopted in [9] to prove [9, Theorem 4.8]. We briefly sketch the main steps, underlining the main differences with respect to the case treated in [9]. The proof is divided into four steps.

Step 1. For every $g \in C^{1,1}(\mathbb{R}; [0, \infty))$, with $g(0) = 0$ and $g(t)$ affine for t sufficiently large, there exists a constant $C_1(g) > 0$, depending on g , $\|u^0\|_0$, and C_1 in (1.9), such that

$$(3.14) \quad \int_0^\infty e^{-s}(g'(s) - g(s))L_\varepsilon(s) ds - \int_0^\infty e^{-s}(4D_\varepsilon(s)g'(s) + K'_\varepsilon(s)g''(s)) ds + R_\varepsilon \geq 0,$$

where

$$R_\varepsilon := \varepsilon g'(0) \int_0^\infty e^{-s} s a(v_\varepsilon(s), u_\varepsilon^1) ds$$

satisfies

$$(3.15) \quad |R_\varepsilon| < C_1(g).$$

In particular, if $\varepsilon\|u_\varepsilon^1\|_0 \rightarrow 0$ as $\varepsilon \rightarrow 0+$, then

$$(3.16) \quad |R_\varepsilon| \rightarrow 0 \quad \text{as } \varepsilon \rightarrow 0+.$$

Using the approximation argument in [9, Corollary 4.5], it is enough to prove (3.14) for $g \in C^2(\mathbb{R}; [0, \infty))$ with $g(0) = 0$ and $g(t)$ constant for t large enough.

For $\delta \geq 0$ small enough, the function $\varphi_\delta(t) := t - \delta g(t)$ is a C^2 -diffeomorphism of $[0, \infty)$ into itself. We consider the function $v_{\varepsilon, \delta}(t) := v_\varepsilon(\varphi_\delta(t)) + t\delta\varepsilon g'(0)u_\varepsilon^1$. By construction $\varphi_\delta(t) \leq t$ so that, in view of (H2), $v_{\varepsilon, \delta} \in \mathcal{V}_\varepsilon^{0,2}$. Note that in the proof of this property the condition $\delta \geq 0$ is crucial. Moreover, $v_{\varepsilon, \delta}(0) = v_\varepsilon(0) = u^0$ and

$$v'_{\varepsilon, \delta}(t)|_{t=0} = v'_\varepsilon(0)(1 - \delta g'(0)) + \delta\varepsilon g'(0)u_\varepsilon^1 = \varepsilon u_\varepsilon^1,$$

whence $v_{\varepsilon, \delta} \in \mathcal{V}_\varepsilon^{0,2}(u^0, \varepsilon u_\varepsilon^1)$.

Set $\psi_\delta(s) := \varphi_\delta^{-1}(s)$ for every $s \geq 0$. By the change of variables $t = \psi_\delta(s)$, it is straightforward to check that

$$(3.17) \quad \begin{aligned} \mathcal{G}_\varepsilon(v_{\varepsilon, \delta}) &= \frac{1}{2\varepsilon^2} \int_0^\infty \psi'_\delta(s) e^{-\psi_\delta(s)} \|v''_\varepsilon(s) |\varphi'_\delta(\psi_\delta(s))|^2 + v'_\varepsilon(s) \varphi''_\delta(\psi_\delta(s))\|^2 ds \\ &\quad + \frac{1}{2} \int_0^\infty \psi'_\delta(s) e^{-\psi_\delta(s)} Q(v_\varepsilon(s) + \delta\varepsilon g'(0)\psi_\delta(s)u_\varepsilon^1) ds. \end{aligned}$$

Notice that

$$(3.18) \quad s = \varphi_\delta(\psi_\delta(s)) = \psi_\delta(s) - \delta g(\psi_\delta(s))$$

so that, in view of the assumptions on g , we have $e^{-\psi_\delta(s)} \leq e^{\delta\|g\|_{L^\infty}} e^{-s}$. Moreover, since

$$\psi'_\delta(s) = 1 + \delta g'(\psi_\delta(s)) \psi'_\delta(s) \quad \text{and} \quad \psi''_\delta(s) = \delta(g''(\psi_\delta(s))(\psi'_\delta(s))^2 + g'(\psi_\delta(s))\psi''_\delta(s)),$$

for δ sufficiently small both $\psi'_\delta(s)$ and $\psi''_\delta(s)$ are bounded uniformly with respect to s . This fact, together with Lemma 3.1, implies that the first integral in (3.17) is finite. As for the second integral we have

$$(3.19) \quad \frac{1}{2} \int_0^\infty \psi'_\delta(s) e^{-\psi_\delta(s)} Q(v_\varepsilon(s) + \delta \varepsilon g'(0) \psi_\delta(s) u_\varepsilon^1) ds \leq \frac{1}{2} \|\psi'_\delta\|_{L^\infty} e^{\delta\|g\|_{L^\infty}} (A_1 + A_2 + A_3),$$

where

$$\begin{aligned} A_1 &:= \int_0^\infty e^{-s} Q(v_\varepsilon(s)) ds \\ A_2 &:= \delta^2 (g'(0))^2 \varepsilon^2 Q(u_\varepsilon^1) \int_0^\infty e^{-s} (\psi_\delta(s))^2 ds \\ A_3 &:= 2\delta \varepsilon g'(0) \int_0^\infty e^{-s} \psi_\delta(s) a(v_\varepsilon(s), u_\varepsilon^1) ds. \end{aligned}$$

Now, $A_1 < \infty$ by (2.3) and $A_2 < +\infty$ in view of (3.18). Finally, by (H5) and the Cauchy inequality, we have $A_3 \leq A_1 + A_2 < \infty$. It follows $\mathcal{G}_\varepsilon(v_{\varepsilon,\delta}) < \infty$ for δ sufficiently small. Analogously, one can show that differentiation under the integral sign in (3.17) is possible.

Since $v_{\varepsilon,0} = v_\varepsilon$ and $v_{\varepsilon,\delta} \in \mathcal{V}_\varepsilon^{0,2}(u^0, \varepsilon u_\varepsilon^1)$ only for $\delta \geq 0$, the minimality of v_ε implies

$$\frac{d}{d\delta} \mathcal{G}_\varepsilon(v_{\varepsilon,\delta}) \Big|_{\delta=0} \geq 0,$$

while in [9] the equality holds. One can compute this derivative as in [9, pages 2031-2032] and one can check that it coincides with the left-hand side of (3.14).

As for R_ε , by assumptions (H3) and (H5) and by (1.9) and (2.2), we have

$$\begin{aligned} |R_\varepsilon| &= \varepsilon |g'(0)| \int_0^\infty e^{-s} s |a(v_\varepsilon(s), u_\varepsilon^1)| ds \\ (3.20) \quad &\leq \varepsilon |g'(0)| \left(\int_0^\infty e^{-s} Q(v_\varepsilon(s)) ds + M_0 \|u_\varepsilon^1\|_0 \int_0^\infty e^{-s} s^2 ds \right) \\ &\leq |g'(0)| (2\varepsilon \mathcal{G}_\varepsilon(v_\varepsilon) + 2M_0 \varepsilon \|u_\varepsilon^1\|_0) \leq 2g'(0) (\varepsilon \bar{C} + C_1) =: C_1(g), \end{aligned}$$

thus proving (3.15). By the last but one inequality in (3.20) and by (2.2), it follows that, if $\varepsilon \|u_\varepsilon^1\|_0 \rightarrow 0$ as $\varepsilon \rightarrow 0+$, then $R_\varepsilon \rightarrow 0$ as $\varepsilon \rightarrow 0+$.

Step 2. $(\mathcal{A}^2 L_\varepsilon)(0) \leq (\mathcal{A} L_\varepsilon)(0) - 4(\mathcal{A} D_\varepsilon)(0) + R_\varepsilon$.

The claim follows by applying (3.14) with $g(t) = t$.

Step 3. $K'_\varepsilon(t) \leq (\mathcal{A} L_\varepsilon)(t) - (\mathcal{A}^2 L_\varepsilon)(t) - 4(\mathcal{A} D_\varepsilon)(t)$ for almost every $t > 0$.

The proof closely resembles the one of [9, Corollary 4.7]. Fix $t > 0$ and for every $\delta > 0$ let $g_{t,\delta}$ be defined by

$$(3.21) \quad g_{t,\delta}(s) := \begin{cases} 0 & \text{if } s \leq t \\ \frac{(s-t)^2}{2\delta} & \text{if } s \in [t, t+\delta] \\ s-t-\frac{\delta}{2} & \text{if } s \geq t+\delta. \end{cases}$$

The claim follows by considering $g = g_{t,\delta}$ in (3.14) and sending $\delta \rightarrow 0$.

Step 4. (3.12) holds true.

In view of Step 2 and (3.6), $\mathcal{A}^2 Q_\varepsilon$ and K_ε are absolutely continuous on the intervals $[0, T]$ for every $T > 0$. Therefore, we can differentiate E_ε and, using Step 3, (3.8), and the very definition of L_ε in (3.1), we get

$$\begin{aligned} E'_\varepsilon &= K'_\varepsilon + (\mathcal{A}^2 Q_\varepsilon)' = K'_\varepsilon + \mathcal{A}^2 Q_\varepsilon - \mathcal{A} Q_\varepsilon \\ &\leq \mathcal{A} L_\varepsilon - \mathcal{A}^2 L_\varepsilon - 4\mathcal{A} D_\varepsilon + \mathcal{A}^2 Q_\varepsilon - \mathcal{A} Q_\varepsilon = -\mathcal{A}^2 D_\varepsilon - 3\mathcal{A} D_\varepsilon \leq 0, \end{aligned}$$

and hence $E_\varepsilon(t) \leq E_\varepsilon(0)$ for a.e. $t \geq 0$. Moreover, by the very definition of E_ε and L_ε , together with (2.3), Step 2, and (3.15), it follows that

$$\begin{aligned} (3.22) \quad E_\varepsilon(0) &= K_\varepsilon(0) + (\mathcal{A}^2 Q_\varepsilon)(0) = \frac{1}{2} \|u_\varepsilon^1\|^2 + (\mathcal{A}^2 Q_\varepsilon)(0) \\ &\leq \frac{1}{2} \|u_\varepsilon^1\|^2 + (\mathcal{A}^2 L_\varepsilon)(0) \leq \frac{1}{2} \|u_\varepsilon^1\|^2 + (\mathcal{A} L_\varepsilon)(0) + R_\varepsilon \\ &= \frac{1}{2} \|u_\varepsilon^1\|^2 + \mathcal{G}_\varepsilon(v_\varepsilon) + R_\varepsilon < C'_1, \end{aligned}$$

where C'_1 depends on $\|u^0\|_0$, $\|u^1\|$, and C_1 in (1.9). This concludes the proof of (3.12). Finally, by using (3.16) and (2.4) in the last line in (3.22), we obtain that, if $\varepsilon \|u_\varepsilon^1\|_0 \rightarrow 0$ as $\varepsilon \rightarrow 0+$, then

$$E_\varepsilon(0) \leq \frac{1}{2} \|u_\varepsilon^1\|^2 + \frac{1}{2} Q(u^0) + r_\varepsilon + R_\varepsilon \leq \frac{1}{2} \|u_\varepsilon^1\|^2 + \frac{1}{2} Q(u^0) + \tilde{r}_\varepsilon,$$

where $\tilde{r}_\varepsilon \rightarrow 0$ as $\varepsilon \rightarrow 0+$. Therefore also (3.13) holds true. \square

4. PROOF OF THEOREM 1.7

Before proving Theorem 1.7, we introduce a suitable subset of $\mathcal{V}_{\varepsilon, T}^{0,2}$, which is dense in $\{\eta \in C_c^2((0, T); V_T) : \eta(t) \in V_t \text{ for every } t \in (0, T)\}$. For every $\varepsilon > 0$ and $T > 0$, we define \mathcal{D}_T as the set of all functions $\eta \in C_c^2((0, T); V_T)$ of the form

$$\eta(t) = \sum_{i=2}^{N-2} \sum_{j=0}^2 \varphi_{i,j}(t) h_{i,j}$$

for some $N \in \mathbb{N}$, $0 = t_0 < t_1 < \dots < t_N = T$, $\varphi_{i,j} \in C^2(\mathbb{R})$ with $\text{supp } \varphi_{i,j} \subset [t_{i-1}, t_{i+1}]$, and $h_{i,j} \in V_{t_{i-1}}$ for $i = 2, \dots, N-2$ and $j = 0, 1, 2$. By (H2) the last two conditions imply that $\eta(t) \in V_t$ for every $t \in [0, T]$. We now prove the density.

Lemma 4.1. *Let $T > 0$. For every $\eta \in C_c^2((0, T); V_T)$. with $\eta(t) \in V_t$ for every $t \in (0, T)$, there exists a sequence $\{\eta_N\} \subset \mathcal{D}_T$ such that*

$$(4.1) \quad \|\eta - \eta_N\|_{C^2([0, T]; V_T)} \rightarrow 0 \quad \text{as } N \rightarrow \infty.$$

Proof. Let $\eta \in C_c^2((0, T); V_T)$, with $\eta(t) \in V_t$ for every $t \in (0, T)$. In order to construct the approximating sequence $\{\eta_N\} \subset \mathcal{D}_T$ we make use of quintic Hermite interpolants, that we construct here through the Bernstein polynomials. Let $N \in \mathbb{N}$ and set $t_i = i \frac{T}{N}$ for $i = 0, 1, \dots, N$. Fix $i = 0, \dots, N$. For $n \in \mathbb{N}$, we define the Bernstein polynomials in the interval $[t_i, t_{i+1}]$ as

$$B_{k,n}^i(t) := \begin{cases} \binom{n}{k} (t - t_i)^k (t_{i+1} - t)^{n-k} & \text{for } k = 0, \dots, n, \\ 0 & \text{for } k < 0 \text{ or } k > n, \end{cases}$$

and we define the polynomials of the spline basis as follows

$$\begin{aligned}\psi_{i,0,+}(t) &:= \frac{N^5}{T^5}(B_{0,5}^i(t) + B_{1,5}^i(t) + B_{2,5}^i(t)), & \psi_{i,0,-}(t) &:= \frac{N^5}{T^5}(B_{3,5}^i(t) + B_{4,5}^i(t) + B_{5,5}^i(t)), \\ \psi_{i,1,+}(t) &:= \frac{N^4}{5T^4}(B_{1,5}^i(t) + 2B_{2,5}^i(t)), & \psi_{i,1,-}(t) &:= -\frac{N^4}{5T^4}(2B_{3,5}^i(t) + B_{4,5}^i(t)), \\ \psi_{i,2,+}(t) &:= \frac{N^3}{20T^3}B_{2,5}^i(t), & \psi_{i,2,-}(t) &:= \frac{N^3}{20T^3}B_{3,5}^i(t).\end{aligned}$$

By construction, it is easy to see that

$$(4.2) \quad \psi_{i,0,+}(t) + \psi_{i,0,-}(t) = 1 \quad \text{for } t \in [t_i, t_{i+1}].$$

Moreover, by using that

$$\frac{d}{dt}B_{k,n}^i(t) = n(B_{k-1,n-1}^i(t) - B_{k,n-1}^i(t)),$$

one can easily show that

$$(4.3) \quad -\frac{T}{N}\psi'_{i,0,+}(t) + \psi'_{i,1,+}(t) + \psi'_{i,1,-}(t) = 1,$$

$$(4.4) \quad -\frac{T^2}{2N^2}\psi''_{i,0,+}(t) + \frac{T}{N}\psi''_{i,1,-}(t) + \psi''_{i,2,+}(t) + \psi''_{i,2,-}(t) = 1.$$

For every $i = 1, \dots, N-1$ and $j = 0, 1, 2$ we set

$$\varphi_{i,j}(t) := \begin{cases} \psi_{i-1,j,-}(t) & \text{if } t \in [t_{i-1}, t_i], \\ \psi_{i,j,+}(t) & \text{if } t \in [t_i, t_{i+1}], \\ 0 & \text{elsewhere.} \end{cases}$$

Finally, we define the function

$$\eta_N(t) := \sum_{i=2}^{N-2} (\varphi_{i,0}(t)\eta(t_{i-1}) + \varphi_{i,1}(t)\eta'(t_{i-1}) + \varphi_{i,2}(t)\eta''(t_{i-1})).$$

By (H2) we have $\eta(t_{i-1}), \eta'(t_{i-1}), \eta''(t_{i-1}) \in V_{t_{i-1}}$, hence $\eta_N \in \mathcal{D}_T$ for every $N \in \mathbb{N}$.

It remains to prove (4.1). Let $t \in \text{supp } \eta$. For $N \in \mathbb{N}$ large enough there exists $i = 2, \dots, N-3$ such that $t \in [t_i, t_{i+1})$, so that by (4.2) and by the very definition of $\eta_N, \psi_{i,1,\pm}$, and $\psi_{i,2,\pm}$, we have

$$\begin{aligned}\|\eta_N(t) - \eta(t)\|_T &\leq \|\psi_{i,0,+}(t)\eta(t_{i-1}) + \psi_{i,0,-}(t)\eta(t_i) - \eta(t)\|_T + \text{O}(1/N) \\ &\leq \|\eta(t_{i-1}) - \eta(t)\|_T + \|\eta(t_i) - \eta(t)\|_T + \text{O}(1/N),\end{aligned}$$

and hence η_N converges to η in V_T uniformly in $[0, T]$. Analogously, by (4.3), we obtain

$$\begin{aligned}\|\eta'_N(t) - \eta'(t)\|_T &\leq \left\| \psi'_{i,0,+}(t)\eta(t_{i-1}) + \psi'_{i,0,-}(t)\eta(t_i) + \frac{T}{N}\psi'_{i,0,+}(t)\eta'(t) \right\|_T \\ &\quad + \|\psi'_{i,1,+}\|_{L^\infty} \|\eta'(t_{i-1}) - \eta'(t)\|_T + \|\psi'_{i,1,-}\|_{L^\infty} \|\eta'(t_i) - \eta'(t)\|_T + \text{O}(1/N),\end{aligned}$$

which, using that (by (4.2)) the first term on the right-hand side is bounded by

$$\frac{T}{N} \|\psi'_{i,0,+}(t)\|_{L^\infty} \left\| -\frac{\eta(t_i) - \eta(t_{i-1})}{T/N} + \eta'(t) \right\|_T,$$

implies that η'_N converges to η' in V_T uniformly in $[0, T]$. Analogously, using (4.2), (4.3), and (4.4), one can show that η''_N converges uniformly to η'' in $[0, T]$. \square

Lemma 4.2. *Let $\varepsilon > 0$ and $T > 0$. For every $\eta \in C_c^2((0, T); V_T)$, with $\eta(t) \in V_t$ for every $t \in (0, T)$, we have*

$$(4.5) \quad \int_0^T e^{-s/\varepsilon} \left(\varepsilon^2 (u_\varepsilon''(s), \eta''(s)) + a(u_\varepsilon(s), \eta(s)) \right) ds = 0.$$

Proof. In view of Lemma 4.1, it is sufficient to prove (4.5) for $\eta \in \mathcal{D}_T$. The proof is analogous to the one of [9, Lemma 5.1]. Let $\delta \in [-1, 1]$ and set $u_{\varepsilon, \delta} := u_\varepsilon + \delta \eta$. By construction, $u_{\varepsilon, \delta} \in \mathcal{V}_T^{0,2}$ and, since η has compact support, also the initial conditions are satisfied. Therefore $u_{\varepsilon, \delta} \in \mathcal{V}^{0,2}(u^0, u_\varepsilon^1)$, and, again by construction, $\mathcal{F}_\varepsilon(u_{\varepsilon, \delta})$ is finite. Then the Euler-Lagrange equation (4.5) easily follows by differentiating $\mathcal{F}_\varepsilon(u_{\varepsilon, \delta})$ with respect to δ at $\delta = 0$. \square

We are now in a position to prove Theorem 1.7.

Proof of Theorem 1.7. Let us fix a sequence $\{\varepsilon_n\} \subset (0, 1)$, with $\varepsilon_n \rightarrow 0$ as $n \rightarrow \infty$. We divide the proof into five steps.

Step 1: *There exist a subsequence, not relabeled, and a function $u \in \mathcal{V}^{0,1}$ such that*

$$(4.6) \quad u_{\varepsilon_n} \rightharpoonup u \quad \text{in } \mathcal{W}_T^{0,1} \quad \text{for every } T > 0.$$

Moreover, $u' \in L^\infty((0, \infty); H)$ and $u \in L^\infty((0, T); V_T)$ for every $T > 0$.

Let $T > 0$. By (1.15) and (1.16),

$$\sup_{n \in \mathbb{N}} \|u_{\varepsilon_n}\|_{H^1((0, T); H)} < \infty.$$

This inequality, together with (H4) and (1.14), implies that there exists $C_T < \infty$ such that

$$\nu_0 \|u_{\varepsilon_n}\|_{L^2((0, T); V_T)}^2 \leq \int_0^T Q(u_{\varepsilon_n}(t)) dt + \lambda_0 \|u_{\varepsilon_n}\|_{L^2((0, T); H)}^2 \leq C_T.$$

As a result $\{u_{\varepsilon_n}\}$ is equibounded in $\mathcal{W}_T^{0,1}$ and hence there exist a subsequence, not relabeled, and a function $u \in \mathcal{W}_T^{0,1}$ such that $u_{\varepsilon_n} \rightharpoonup u$ weakly in $\mathcal{W}_T^{0,1}$. Moreover, since $\{u_{\varepsilon_n}\} \subset \mathcal{V}_T^{0,2} \subset \mathcal{V}_T^{0,1}$ and $\mathcal{V}_T^{0,1}$ is a closed subspace of $\mathcal{W}_T^{0,1}$, we have that $u \in \mathcal{V}_T^{0,1}$. By the arbitrariness of T , the function u belongs to $\mathcal{V}^{0,1}$ and (4.6) holds true. Furthermore, in view of (4.6), inequality (1.16) implies $u' \in L^\infty((0, \infty); H)$ and (1.15) gives $u \in L^\infty((0, T); V_T)$ for every $T > 0$.

Step 2: *Let $T > 0$. For every $\psi \in C_c^\infty((0, T); V_T)$, with $\psi(t) \in V_t$ for every $t \in (0, T)$, we have*

$$(4.7) \quad \int_0^T (u'_{\varepsilon_n}(t), \varepsilon_n^2 \psi'''(t) + 2\varepsilon_n \psi''(t) + \psi'(t)) dt = \int_0^T a(u_{\varepsilon_n}(t), \psi(t)) dt.$$

The claim follows by considering $\eta(t) = e^{t/\varepsilon_n} \psi(t)$ in (4.5) and integrating by parts.

Step 3: *u is a weak solution of (1.7).* By [4, Lemma 2.8], it is enough to prove the claim for $\psi \in C_c^\infty((0, T); V_T)$ with $\psi(t) \in V_t$ for every $t \in (0, T)$. In view of (4.6), one can pass to the limit as $n \rightarrow \infty$ in (4.7), thus obtaining (1.8).

Step 4: *u satisfies (a) and (b).* Since $u' \in L^\infty((0, \infty); H)$ and $u \in L^\infty((0, T); V_T)$ for every $T > 0$ by Step 1, property (a) follows from Step 3, thanks to Remark 1.4. Claim (b) is obtained by combining (a), (1.9), and (4.6), together with the fact that $u_{\varepsilon_n} \in \mathcal{V}^{0,1}(u^0, u_{\varepsilon_n}^1)$.

Step 5: *u satisfies the energy inequality (1.17).* By using [9, Lemma 6.1] and (3.13), one can argue as in [9, Section 6] to obtain that the energy inequality (1.17) is satisfied for almost every $t > 0$. Actually, in view of (a), this inequality is satisfied for every $t > 0$. \square

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